General Description

The GAM-1818F2LBZ-AGGB is a receiving module that supports single-band and multi-mode. It has built-in highly integrated GNSS receiver chip, supports multi band and multi system cm4f (main frequency 428MHz, 22nm Technology) chip of Third-generation BeiDou Navigation Satellite System (BDS-3). Besides, it is capable of tracking all global civil navigation systems (BDS, GPS, GLONASS, Galileo, QZSS and SBAS) in all bands.

GAM-1818F2LBZ-AGGB module is based on the state of art CYNOSURE III architecture, integrating single-band and multi-system GNSS RF and baseband. This newly designed architecture makes this single chip achieve sub-meter level position accuracy without correction data from ground-based augmentation station and higher sensitivity, improves the sensitivity and anti-interference ability, enhances the multipath performance, and provides accurate and reliable positioning service in complex environment.

GAM-1818F2LBZ-AGGB module contains MediaTek AG3352Q positioning engine inside, featuring high sensitivity, low power consumption, and fast TTFF. The superior cold start sensitivity allows it to acquire, track, and get position fix autonomously in difficult weak signal environment. The receiver's superior tracking sensitivity allows continuous position coverage in nearly all outdoor application environments. The high performance signal parameter search engine is capable of testing 16 million time-frequency hypotheses per second, offering superior signal acquisition and TTFF speed.

Applications

- LBS (Location Based Service)
- PND (Portable Navigation Device)
- Vehicle navigation system
- Mobile phone

Figure: GAM-1818F2LBZ-AGGB Top View

Features

- Build on high performance, low-power MediaTek AG3352Q chip set
- Ultra high track sensitivity: -165dBm
- Concurrent reception of single-band and multi-system satellite signals
- Supports all civil GNSS signals
- Supports BDS-3 signal
- Extremely fast TTFF at low signal level
- Multipath detection and suppression
- Works with passive and active antenna
- Low power consumption: 12mA@3.3V
- NMEA-0183 compliant protocol or custom protocol
- Operating voltage:3.0V~5.5V
- Small form factor: 18.3±0.5x18.4±0.5x7.4±0.5mm
- Operating temperature -40 ~ +85ºC
- RoHS compliant (Lead-free)

1. Functional Description

1.1. Key Features

Table 1: Key Features

Parameter	Specification
GNSS engine	• GNSS engine has 47SVs channels and DSP accelerators
GNSS reception	• GPS/QZSS: L1 C/A, L1C • BDS: B1I,B1C • GLONASS: L1 • Galileo: E1 • SBAS: WAAS, EGNOS, MSAS, GAGAN
Update rate	• GNSS 10Hz Maximum ; 1Hz by default
Position accuracy	• GNSS <1.5m CEP • SBAS <1.5m CEP
Velocity & Time accuracy	• GNSS 0.01m/s CEP • SBAS 0.05 m/s • 1PPS 10 ns
Time to First Fix(TTFF)	• Hot start <5 sec • Cold start 25 secs
Sensitivity	• Cold start -149dBm • Hot start -155dBm • Re-acquisition -158dBm • Tracking & navigation -165dBm
GNSS Operating limit	• Velocity 100m/s(10m/s Minimum) • Altitude 10,000m(80000m Maximum)
Datum	• Default WGS-84, User definable
UART Port	• UART Port: TXD and RXD • Supports baud rate from 9600bps to 961200bps.115200bps by default • NMEA 0183 Protocol Ver. 4.00/4.10,Cynosure GNSS Receiver Protocol
Temperature Range	• Normal operation: -40°C ~ +85°C • Storage temperature: -55°C ~ +90°C • Humidity: 5% ~ 95%
Physical Characteristics	• Size: 18.3±0.5x18.4±0.5x7.4±0.5mm • Weight: Approx.7.4g

1.2 Power Supply

Regulated power for the GAM-1818F2LBZ-AGGB is required. The VCC Pin Need a stable DC voltage supply. Power supply ripple must be less than 30mV. The input voltage Vcc should be 3.0V~5.5V, Recommended power supply voltage is 3.3V . maximum current is 12mA. Suitable decoupling must be provided by external decoupling circuitry.

1.3 UART Ports

The module supports two full duplex serial channels UART. All serial connections are at 3V CMOS logic levels, if need different voltage levels, use appropriate level shifters. The baud rate of both serial ports are fully programmable, the data format is however fixed: X, N, 8, 1, i.e. X baud rate, no parity, eight data bits and one stop bit, no other data formats are supported, LSB is sent first. The modules default baud rate is set up 115200bps, however, the user can change the default baud rate to any value from 9600 bps to 961200bps. UART port can be used for firmware upgrade, NMEA output and PMTK proprietary commands input.

2. Application

The GAM-1818F2LBZ-AGGB module is equipped with a 4-pin connector or 4 pin pads that connects to your application platform. It consists of a Media-Tek AG3352Q single chip GPS IC which includes the RF part and Baseband part, a patch antenna, a LNA, a SAW filter, a TCXO, a crystal oscillator. Also comes with a 0.22F crystal capacitor ,can backup satellite ephemeris about 2 hour.

2.1. Pin Assignment

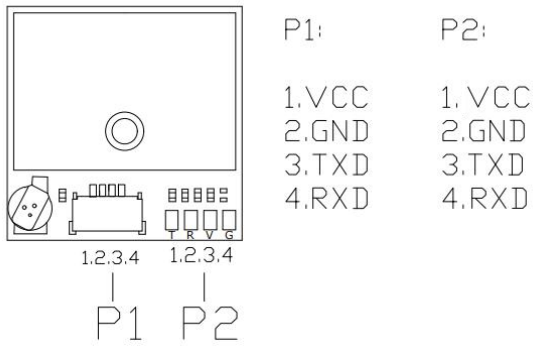


Figure 2: Pin Assignment

Table 2: P1 Pin Description

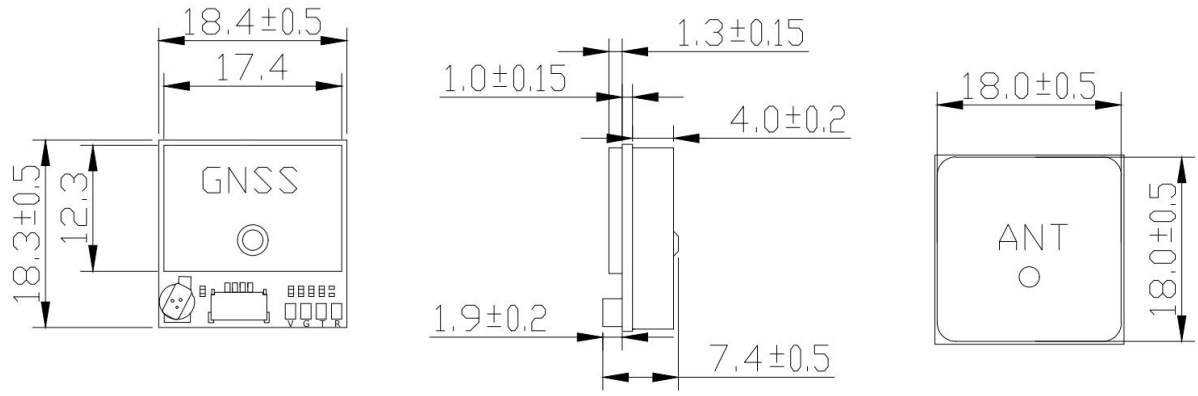
Pin No.	Pin name	I/O	Description	Remark
1	VCC	I	Module Power Supply	Voltage range: 3.0V~5.5V
2	GND	G	Ground	
3	TXD	O	UART Serial Data output	
4	RXD	I	UART Serial Data Input	

Table 3: P2 Pin Description

Pin No.	Pin name	I/O	Description	Remark
1	VCC	I	Module Power Supply	Voltage range: 3.0V~5.5V
2	GND	G	Ground	
3	TXD	O	UART Serial Data output	
4	RXD	I	UART Serial Data Input	

2.2 Mechanical Dimensions

This chapter describes the mechanical dimensions of the GAM-1818F2LBZ-AGGB module. Size unit（mm）



Front view　　Rear view　　Profile view

Figure 3:GAM-1818F2LBZ-AGGB Specification size chart

3. NMEA 0183 Protocol

The output protocol supports NMEA-0183 standard. The implemented messages include GGA, GLL, GSA, GSV, VTG, RMC messages. The NMEA message output has the following sentence structure:$AACCC，c-c*hh

The detail of the sentence structure is explained in Table 1.

Table 4: The NMEA sentence structure

character	HEX	Description
“$”	24	Start of sentence.
Aaccc		Address field. “aa” is the talker identifier. “ccc” identifies the sentence type.
“,”	2C	Field delimiter.
C–c		Data sentence block.
“*”	2A	Checksum delimiter.

Hh		Checksum field.
<CR><LF>	0D0A	Ending of sentence. (carriage return, line feed)

Table 5: Overview of NMEA messages

$GNGGA	Time, position, and fix related data of the receiver.
$GNGLL	Position, time and fix status.
$GNGSA	Used to represent the ID of satellites which are used for position fix. When GPS&GLONASS&Galileo & BDS satellites are used for positioning solutions, the ID of available positioning satellites is counted and output with multiple statements.
$GPGSV **$GLGSV** **$GAGSV** **$GBGSV**	Satellite information about elevation, azimuth and CNR, satellites are used in position solution, a $GPGSV sentence is used for GPS satellites, a $GLGSV sentence is used for GLONASS satellites, a $GAGSV sentence is used for GALILEO satellites. And $GBGSV sentence is used for BDS satellites.
$GNRMC	Time, date, position, course and speed data.
$GNVTG	Course and speed relative to the ground.

✧ **The formats of the supported NMEA messages are described as follows:**

GNRMC,GNVTG,GNGGA,GNGLL,GNGSA,GPGSV,GLGSV,GAGSV,GBGSV

3.1 GGA – Global Positioning System Fix Data

Time, position and fix related data for a GNSS receiver.

Structure:$GNGGA,hhmmss.sss,ddmm.mmmm,a,dddmm.mmmm,a,x,xx,x.x,x.x,M,x.x,M,x.x,xxxx*hh

For example:$GNGGA,175258.000,2447.0870,N,12100.5221,E,2,15,0.7,95.2,M,19.6,M,,0000*72

Field	Name	Example	Description
1	UTC Time	175258.000	UTC of position in hhmmss.sss format, (000000.000 ~ 235959.999)
2	Latitude	2447.08700	Latitude in ddmm.mmmmm format Leading zeros transmitted
3	N/S Indicator	N	Latitude hemisphere indicator, ‘N’ = North, ‘S’ = South
4	Longitude	12100.52210	Longitude in dddmm.mmmmm format Leading zeros transmitted
5	E/W Indicator	E	Longitude hemisphere indicator, ‘E’ = East, ‘W’ = West
6	Quality Indicator	2	Quality Indicator 0: position fix unavailable 1: valid position fix, SPS mode 2: valid position fix, differential GPS mode 3: GPS PPS Mode, fix valid 6: Estimated (dead reckoning) Mode
7	Satellites Used	15	Number of satellites in use, (00 ~ 56)
8	HDOP	0.7	Horizontal dilution of precision, (0.0 ~ 99.9)
9	Altitude	95.2	mean sea level (geoid), (- 9999.9 ~ 17999.9)
10	Geoidal Separation	19.6	Geoidal separation in meters

11	Age pf Differential GPS data		Age of Differential GPS data NULL when DGPS not used
12	DGPS Station ID	0000	Differential reference station ID, 0000 ~ 1023
13	Checksum	72	

3.2 GLL – Latitude/Longitude

Latitude and longitude of current position, time, and status.

Structure:$GNGLL,ddmm.mmmm,a,dddmm.mmmm,a,hhmmss.sss,A,a*hh

For example:$GNGLL,2447.0870,N,12100.5221,E,175258.000,A,D*42

Field	Name	Example	Description
1	Latitude	2447.08700	Latitude in ddmm.mmmmm format Leading zeros transmitted
2	N/S Indicator	N	Latitude hemisphere indicator 'N' = North , 'S' = South
3	Longitude	12100.52210	Longitude in dddmm.mmmmm format Leading zeros transmitted
4	E/W Indicator	E	Longitude hemisphere indicator 'E' = East , 'W' = West
5	UTC Time	175258.000	UTC time in hhmmss.sss format (000000.000 ~ 235959.999)
6	Status	A	Status, 'A' = Data valid, 'V' = Data not valid
7	Mode Indicator	D	Mode indicator 'N' = Data not valid 'A' = Autonomous mode 'D' = Differential mode 'E' = Estimated (dead reckoning) mode
8	Checksum	42	

3.3 GSA – GNSS DOP and Active Satellites

GNSS receiver operating mode, satellites used in the navigation solution reported by the GGA sentence and DOP values.

Structure:$GNGSA,A,x,xx,xx,xx,xx,xx,xx,xx,xx,xx,xx,xx,xx,xx,x.x,x.x,x.x,x*hh

For example:$GNGSA,A,3,21, 12,15,18,20,24,10,32,25,13,,,1.2,0.7,1.0,1*18

Field	Name	Example	Description
1	Mode	A	Mode 'M' = Manual, forced to operate in 2D or 3D mode 'A' = Automatic, allowed to automatically switch 2D/3D
2	Mode	3	Fix type 1 = Fix not available 2 = 2D 3 = 3D
3	Satellite used 1~12	21, 12, 15, 18, 20, 24, 10, 32, 25, 13	01 ~ 32 are for GPS; 33 ~ 64 are for WAAS (PRN minus 87); 193 ~ 197 are for QZSS; 65 ~ 88 are for GLONASS (GL PRN) ; 01 ~ 36 are for GALILEO (GA PRN); 01 ~ 37 are for BDS (BD PRN). GPS,

			GLONASS, GALILEO and BDS satellites are differentiated by the GNSS system ID in table 5. Maximally 12 satellites are included in each GSA sentence
4	PDOP	1.2	Position dilution of precision (0.0 to 99.9)
5	HDOP	0.7	Horizontal dilution of precision (0.0 to 99.9)
6	VDOP	1.0	Vertical dilution of precision (0.0 to 99.9)
7	GNSS System ID	1	1 for GPS, 2 for GLONASS, 3 for GALILEO, 4 for BDS
8	Checksum	18	

3.4 GSV – GNSS Satellites in View

Number of satellites (SV) in view, satellite ID numbers, elevation, azimuth, and SNR value. Four satellites maximum per transmission.

Structure:$GPGSV，x，x，xx，xx，xx，xx，xx，...，xx，xx，xx，xx，xx，x*hh

For example:$GPGSV，4,1，13，02,72，109，43,24，69,035，48,18，52,330，42,21，49,246，43，1*69

Field	Name	Example	Description
1	Number of message	4	Total number of GSV messages to be transmitted (1 - 5)
2	Sequence number	1	Sequence number of current GSV message
3	Satellites in view	13	Total number of satellites in view (00 ~ 20)
4	Satellite ID	02	01 ~ 32 are for GPS; 33 ~ 64 are for WAAS (PRN minus 87); 193 ~ 197 are for QZSS; 65 ~ 88 are for GLONASS (GL PRN) ; 01 ~ 36 are for GALILEO (GA PRN); 01 ~ 37 are for BDS (BD PRN). GPS, GLONASS, GALILEO and BDS satellites are differentiated by the GNSS system ID in table 5. Maximally 12 satellites are included in each GSV sentence
5	Elevation	72	Satellite elevation in degrees, (00 ~ 90)
6	Azimuth	109	Satellite azimuth angle in degrees, (000 ~ 359)
7	SNR	43	C/No in dB (00 ~ 99) Null when not tracking
8	Signal ID	1	1 for L1/CA
9	Checksum	69	

3.5 RMC – Recommended Minimum Specific GNSS Data

Time, date, position, course and speed data provided by a GNSS navigation receiver.

Structure:$GNRMC,hhmmss.sss,A,dddmm.mmmm,a,dddmm.mmmm,a,x.x,x.x,ddmmyy,,,a*hh

For example:$GNRMC,175258.000,A,2447.0870,N,12100.5220,E,000.0,000.0,220617,,,D*75

Field	Name	Example	Description
1	UTC time	175258.000	UTC time in hhmmss.sss format (000000.00 ~ 235959.999)
2	Status	A	Status 'V' = Navigation receiver warning 'A' = Data Valid

3	Latitude	2447.08700	Latitude in dddmm.mmmmm format Leading zeros transmitted
4	N/S indicator	N	Latitude hemisphere indicator 'N' =North , 'S' = South
5	Longitude	12100.52210	Longitude in dddmm.mmmmm format Leading zeros transmitted
6	E/W Indicator	E	Longitude hemisphere indicator 'E' = East , 'W' = West
7	Speed over ground	000.0	Speed over ground in knots (000.0 ~ 999.9)
8	Course over ground	000.0	Course over ground in degrees (000.0 ~ 359.9)
9	UTC Date	220617	UTC date of position fix, ddmmyy format
10	Mode indicator	D	Mode indicator 'N' = Data not valid 'A' = Autonomous mode 'D' = Differential mode 'E' = Estimated (dead reckoning) mode
11	checksum	75	

3.6 VTG – Course Over Ground and Ground Speed

The actual course and speed relative to the ground.

Structure: GNVTG,x.x,T,,M,x.x,N,x.x,K,a*hh

For example:$GNVTG,000.0,T,,M,000.0,N,000.0,K,D*16

Field	Name	Example	Description
1	Course	000.0	True course over ground in degrees (000.0 ~ 359.9)
2	Speed	000.0	Speed over ground in knots (000.0 ~ 999.9)
3	Speed	000.0	Speed over ground in kilometers per hour (000.0 ~ 1800.0)
4	Mode	D	Mode indicator 'N' = Data not valid 'A' = Autonomous mode 'D' = Differential mode 'E' = Estimated (dead reckoning) mode
5	Checksum	16	

Gotop Technology Co. ， LTD

Add:AreaC,4th layer,A1 building,QingHu Silicon Valley Power,LongHua district ,Shenzhen ,China
Phone: 86-755-23804156
fax: 86-755-23804155
N 22° 32' 17", E 114° 07' 07“
http://www.gotop-zzu.com